



EUROPEAN UNIVERSITY OF LEFKE

Electrical and Electronics Engineering, Faculty of Engineering

SYLLABUS

2020-2021 Spring Semester

Course Code	Course Name	Course Type	Weekly Course Hours			Credits	ECTS	Weekly Time Schedule
			T	A	L			
EE322	Control Systems	Major	3	0	0	3	6	Wednesday, 15:00-17:50. ONLINE
Prerequisite		Prerequisite to						
Course Lecturer	Soydan Redif					Office Hours Schedule		
E-mail						Office / Room No		
Phone						Phone		
Teaching Assistant	Ahmet Yasli					Office / Room No		
E-mail	ayasli@eul.edu.tr							
Catalogue Descriptions	Open loop and closed loop control. Transfer function, block diagram, signal flow graph, state equations. Sensitivity, disturbance rejection, steady-state error. Second- and first-order system performance, dominant roots, steady-state error of feedback systems. Routh-Hurwitz criterion, relative stability. Root locus method. Bode diagram, Nyquist stability criterion, gain margin and phase margin. PI, PD and PID controller design.							
Course Objectives	To establish the concept of the general processes involved in the design and analysis of linear control systems. Having successfully completed the module, the student will be able to: (i) Obtain the mathematical model and/or transfer function of linear control systems; (ii) Apply time and frequency domain techniques for the analysis of linear systems; (iii) Use the control point of view to analyse problems arising in other disciplines. Course material will be complemented with in-class MATLAB demonstrations.							
Learning Outcomes	On successful completion of the course, students should understand: (1) mathematical modelling of linear control systems, e.g. transfer functions, (2) the theoretical tools required for basic control system analysis, (3) techniques for stability analysis of control systems, (4) frequency domain techniques for the analysis of linear systems.							
Textbooks	1	R. C. Dorf and R. H. Bishop, Modern Control Systems 13th Ed, Pearson - Prentice Hall 2016. ISBN: 0134407628						
	2	N. S. Nise, Control Systems Engineering, 3rd Ed., John Wiley & Sons, 2014. ISBN: 1118170512						
WEEK	Date	TOPICS					Reference No - Section	
Week 1	01-05/03/21	Open loop and closed loop control					1: 1.1-1.8	
Week 2	08-12/03/21	Modeling: integro-differential equations					1: 2.1-2.4	
Week 3	15-19/03/21	System block diagram description					1: 2.5-2.9	
Week 4	22-26/03/21	Signal flow graphs, state space equations					1: 3.1-3.4	
Week 5	29-02/03-04/21	Laplace transforms					1: 3.3; 3.5-3.7	
Week 6	05-09/03/21	Laplace transform and transfer functions					1: 4.1-4.4;4,6	
Week 7	10-18/04/21	Midterm Exam					-	
Week 8	19-23/04/21	Feedback control system performance					1: 5.1-5.4	
Week 9	26-30/04/21	Feedback control system characteristics: steady-state, type.					1: 5.2; 5.5-5.6; 5.9	
Week 10	03-07/05/21	Root locus method - introduction					1: 6.4-6.6	
Week 11	10-14/05/21	Root locus method - system stability analysis					1: 7.1-7.3	
Week 12	17-21/05/21	Frequency response methods: Bode diagrams I					1: 7.3; 7.6-7.8	
Week 13	24-28/05/21	Frequency response methods: Bode diagram II					1: 8.1-8.3	
Week 14	31-04/05-06/21	Frequency response methods: Nyquist stability criterion I					1: 8.1-8.3	
Week 15	07-11/06/21	Frequency response methods: Nyquist stability criterion II					1: 8.1-8.3	
Week 16	12-21/06/21	Final Exam					-	
Evaluation Tools	Evaluation Tool	Quantity	Date		Weight in Total (%)	Weight in Semester Evaluation (%)		
	Final Exam	1	12-21/06/21		50			
	Semester Evaluation				50			
	Midterm(s)	1	10-18/04/21		25	50.0		
	Quiz(zes)							
	Project(s)							
	Homework(s)							
Laboratory works	1			25	100.0			